

## 1 Features and Benefits

- Wide operating voltage range: from 3.3V to 18V
- Less than 10 $\mu$ A average supply current in  $\mu$ -Power Mode
- Flexible magnetic thresholds and temperature coefficient
- Integrated self-diagnostic functions activating dedicated Safe Mode
- Reverse supply voltage protection
- Under-Voltage Reset protection
- Thermal protection
- Optional IMC integration for lateral sensing
- Customer end-of-line programming
- Wide programmable magnetic Latch/Switch range
- Developed according to ISO26262-10, 9 as safety HW element out of context with ASIL-B level
- MLX92292 = Programmable with PTC04 (unlocked)  
MLX92291/71 = Melexis Pre-programmed SW/L

## 2 Application Examples

- Automotive, Consumer and Industrial
- Brake light/ wake-up switch
- e-door Handle
- Charging Flap
- Seat positioning
- Sunroof/Tailgate opener
- Transmission applications (PRNDL, Drive Mode Select, Neutral)
- Electronic Steering Column Lock
- Electrical power steering

## 3 Ordering Information

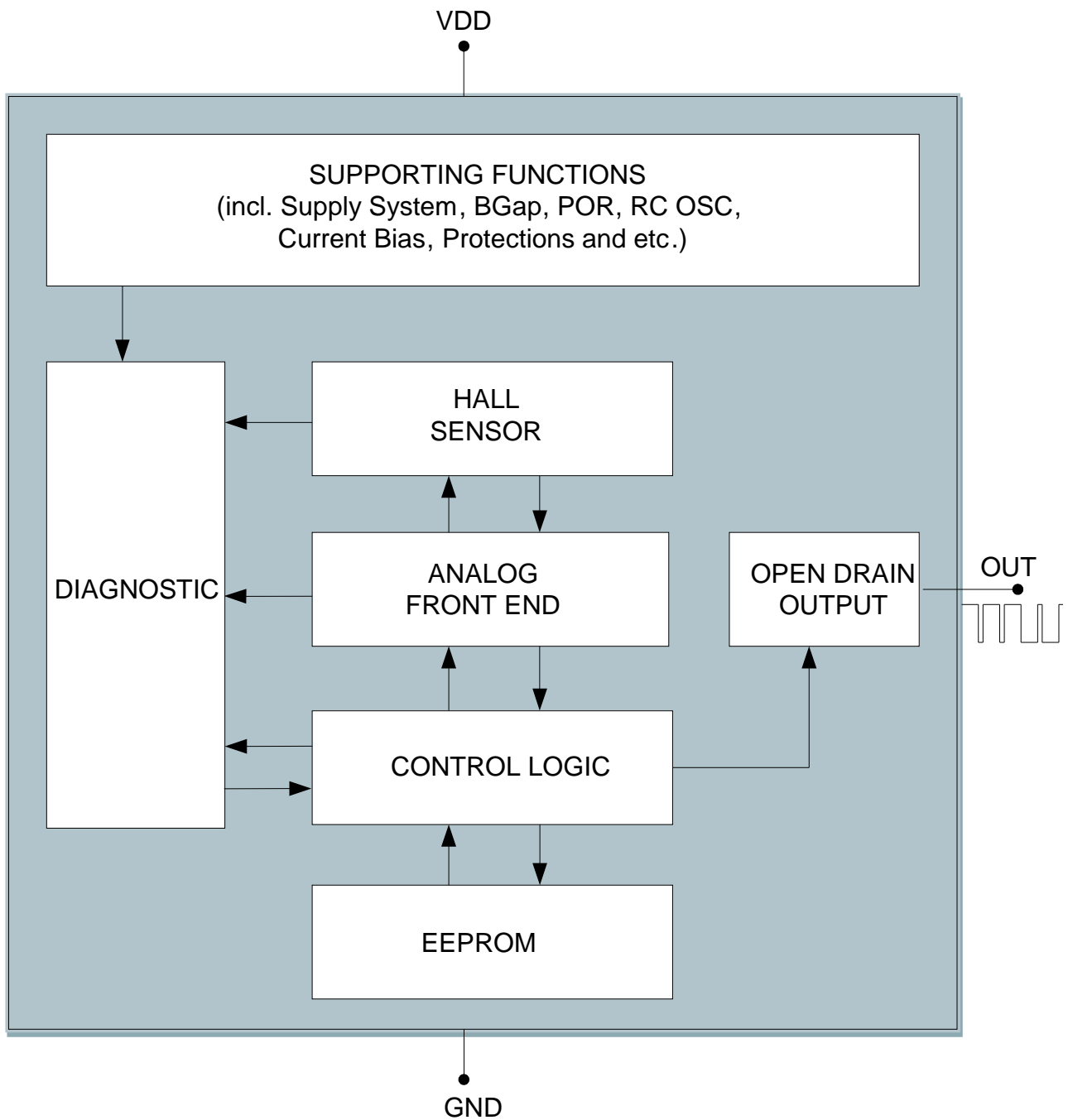
Product Code	Temperature Code	Package Code	Option Code	Packing Form Code
MLX92292	L	SE	AAA-000	RE
MLX92292	L	UA	AAA-000	BU
MLX92292	L	SE	AAA-200	RE
MLX92292	L	DC	AAA-000	RE
MLX92271	L	UA/SE	AAA-xxx	BU/SE
MLX92291	L	UA/SE	AAA-xxx	BU/SE

In the table above only the programmable (MLX92292) versions are highlighted. These as programmable variants which can be used for prototyping or programming in the application. An example is given for MLX92271 (pre-programmed latch) and MLX92291 (pre-programmed switch). Please refer to section 8 for the released available variants.

### Legend:

Product Code:	MLX92292 (programmable), MLX92271 (Latch), MLX92291 (switch)
Temperature Code:	L (-40°C to 150°C)
Package Code:	SE = TSOT-3L UA = TO92-3L DC = SOIC-8 (dual die)
Option Code:	0xx => normal version (perpendicular sensitive) 2xx => IMC version (lateral sensitive)
Packing Form:	BU=Bulk   RE = Reel   CA = Ammopack   CR = Carton on Reel
Ordering example:	MLX92292LSE-AAA-000-RE

## 4 Functional Diagram



## 5 General Description

Melexis has made a major advance in magnetic sensing technology that will have widespread implications for modern automobile design the MLX92292 - effectively represents a whole new way of sensing. This device delivers switch functions, but unlike existing products on the market it can determine the presence of magnetic fields that are lateral, not just orthogonal, to it. The uniqueness of this offering is taken further by the fact that the MLX92292 switch is supporting an ASIL B safety integrity level (in accordance with ISO 26262), with an array of built-in diagnostic mechanisms available.

Flexibility is a key attribute of the MLX92292. OEM customers can choose straightforward pre-programmed units, or alternatively they can benefit from the end-of-line (EoL) programming capacity. Through this each device may be configured (via its output pin) during the OEM production process, so system optimization is fully realized. The programming facility also enables setting of both magnetic operating points to small increments across a range spanning -90mT to +90mT (-40mT to +40mT for lateral sensing versions).

The MLX92292 can be specified with standard orthogonal sensitivity or the lateral sensitivity option. The upshot of lateral sensitivity being that there is potential to replace multiple devices with a single surface mount unit, thereby saving valuable board space and lowering bill-of-materials costs. This stems directly from Melexis' proprietary Integrated Magnetic Concentrator (IMC™) technology, which enables substantial heightening of signal-to-noise ratios in magnetic field measurement. In addition, the capacity of this technology to sense laterally allows lower profile system implementations, as the magnet can move alongside the device rather than having to be above it.

Safeguarding the MLX92292 are reverse supply voltage, thermal, electro-static discharge (ESD) and over-voltage protections, plus Under-Voltage Reset features. With the capacity to deal with a 40V load dump, it can be connected directly to the vehicle battery. In order to achieve ASIL B compliance, numerous diagnostic/monitoring functions have been incorporated, including Hall sensor and analog frontend diagnostics. The device comprises a full set of programmable reporting features, giving it compatibility with any existing electronic control unit (ECU) interface. Only the normal application pins are required for this - without need of additional diagnostic pins and thus simplifying the design concept considerably.

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## 6 Absolute Maximum Ratings

Parameter	Symbol	Value	Units
Supply voltage <sup>(1, 2)</sup>	V <sub>DD</sub>	+28V	V
Supply voltage (Load Dump) <sup>(1, 4)</sup>	V <sub>DD</sub>	+ 45V	V
Supply current <sup>(1, 2, 3)</sup>	I <sub>DD</sub>	+20	mA
Supply current <sup>(1, 3, 4)</sup>	I <sub>DD</sub>	+50	mA
Reverse supply voltage <sup>(1, 2)</sup>	V <sub>DDREV</sub>	-24	V
Reverse supply voltage <sup>(1, 4)</sup>	V <sub>DDREV</sub>	-30	V
Reverse supply current <sup>(1, 2, 5)</sup>	I <sub>DDREV</sub>	-20	mA
Reverse supply current <sup>(1, 4, 5)</sup>	I <sub>DDREV</sub>	-40	mA
Output voltage <sup>(1, 2)</sup>	V <sub>OUT</sub>	+28	V
Reverse output voltage <sup>(1)</sup>	V <sub>OUTREV</sub>	-0.5	V
Reverse output current <sup>(1, 2)</sup>	I <sub>OUTREV</sub>	-50	mA
Maximum junction temperature <sup>(6)</sup>	T <sub>J</sub>	+165	°C
ESD sensitivity – HBM <sup>(7)</sup>	-	8	kV
ESD sensitivity – CDM <sup>(8)</sup>	-	1000	V

Exceeding the absolute maximum ratings may cause permanent damage. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

<sup>1</sup> The maximum junction temperature should not be exceeded

<sup>2</sup> For maximum 1 hour

<sup>3</sup> Including current through protection device

<sup>4</sup> For maximum 500ms

<sup>5</sup> Through protection device

<sup>6</sup> For 1000 hours.

<sup>7</sup> Human Body Model according AEC-Q100-002 standard

<sup>8</sup> Charged Device Model according AEC-Q100-011 standard

## 7 General Electrical Specifications

DC Operating Parameters  $V_{DD} = 3.3V$  to  $18V$ ,  $T_A = -40^\circ C$  to  $150^\circ C$  (unless otherwise specified)

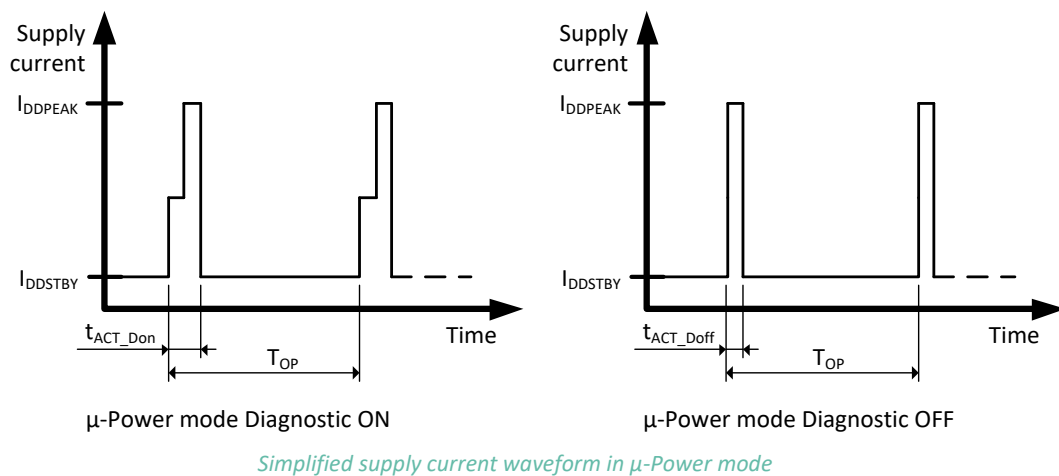
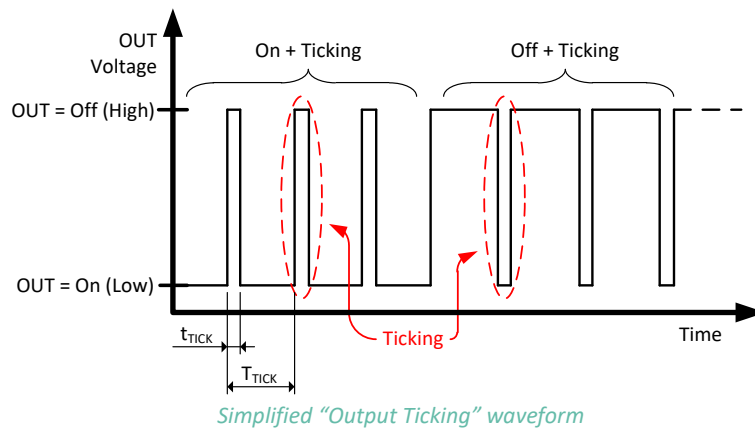
Parameter	Symbol	Test Conditions	Min	Typ <sup>(1)</sup>	Max	Units
Under-Voltage Reset threshold	$V_{UVR}$	$V_{DD}$ monitoring during Active phase	1.8	2.5	3	V
UVR reaction time <sup>(2)</sup>	$t_{UVR}$	$V_{DD}$ monitoring during Active phase, $V_{DD} = V_{UVR} - 0.3V$	—	1	—	$\mu s$
Minimum supply voltage for defined output state <sup>(2)</sup>	$V_{DD1}$	$R_{PU} = 2.2k\Omega$ , $V_{PU} = 5V$	—	1	1.2	V
Output leakage <sup>(6)</sup>	$I_{OFF}$	$V_{OUT} = 18V$ , $T_A = -40..85^\circ C$	—	0.1	1	$\mu A$
Output leakage	$I_{OFF}$	$V_{OUT} = 18V$	—	—	5	$\mu A$
Output saturation voltage	$V_{OL}$	Fast Mode, $I_{OL} = 20mA$	0.1	0.25	0.7	V
Output saturation voltage	$V_{OL}$	$\mu$ -Power Mode, $I_{OL} = 10mA$	—	0.15	0.5	V
Continuous output current	$I_{OL}$	Fast mode	—	—	30	mA
		$\mu$ -Power Mode	—	—	15	
Output Rise Time <sup>(2,5)</sup> ( $R_{PU}$ dependent)	$t_R$	$R_{PU} = 2.2k\Omega$ , $V_{DD} = 12V$ , $V_{PU} = 5V$ $C_{LOAD} = 50pF$ to GND	0.3	0.6	1	$\mu s$
Output Fall Time <sup>(2,5)</sup> (On-chip controlled)	$t_F$	$R_{PU} = 2.2k\Omega$ , $V_{DD} = 12V$ , $V_{PU} = 5V$ $C_{LOAD} = 50pF$ to GND	0.3	0.6	1	$\mu s$
Power-On time <sup>(3,4)</sup>	$t_{ON}$	$V_{DD} = 5V$ , $dV_{DD}/dt > 2V/\mu s$	—	0.5	1	ms
Power-On state	-	Output state during $t_{ON}$	High			—
Output update period	$T_{UPD}$	Fast Mode	—	40	45	$\mu s$
Programmable operating (output update) period	$T_{OP}$	$\mu$ -Power Mode, typical range	0.16 <sup>(1)</sup>	—	260 <sup>(1)</sup>	ms
Operating period 1 (1 <sup>st</sup> ref. value)	$T_{OP1}$	$\mu$ -Power Mode	196	222	246	ms
Operating period 2 (2 <sup>nd</sup> ref. value)	$T_{OP2}$	$\mu$ -Power Mode	40	45	50	ms
Programmable diagnostic period in Fail Safe state	$T_{DP}$	Fast Mode, typical range	0.13 <sup>(1)</sup>	—	260 <sup>(1)</sup>	ms
Programmable "Output Ticking" repetition period	$T_{TICK}$	Equal to (multiple of) $T_{OP}$ , typical range	0.6 <sup>(1)</sup>	—	260 <sup>(1)</sup>	ms
Programmable "Output Ticking" duration	$t_{TICK}$	Typical range	4	—	128	$\mu s$
Active phase duration, diagnostic On	$t_{ACT\_Don}$	$\mu$ -Power Mode, defined at $I_{DD} > 0.7mA$	—	40	—	$\mu s$
Active phase duration, diagnostic Off	$t_{ACT\_Doff}$	$\mu$ -Power Mode, defined at $I_{DD} > 0.7mA$	—	24	—	$\mu s$
Tolerance of operating period ratio $t_{ACT}/T_{OP}$	$R_{TOL}$	$\mu$ -Power Mode	-5	0	5	%
Active phase supply current, diagnostic On (average value)	$I_{DDACT\_Don}$	$\mu$ -Power Mode	1.8	2.4	2.9	mA
Active phase supply current, diagnostic Off (average value)	$I_{DDACT\_Doff}$	$\mu$ -Power Mode	2.2	3	3.5	mA
Standby phase supply current <sup>(8)</sup>	$I_{DDSTBY}$	$V_{DD} \leq 16V$ , $T_A = -40..85^\circ C$	—	6	9	$\mu A$
Standby phase supply current	$I_{DDSTBY}$	$V_{DD} \leq 16V$	—	6	27	$\mu A$
Average supply current <sup>(8,9)</sup>	$I_{DDAVG1}$	$V_{DD} \leq 16V$ , $T_A = -40..85^\circ C$ , $T_{OP} = T_{OP1}$	—	6.4	9.5	$\mu A$
Average supply current <sup>(8,9)</sup>	$I_{DDAVG2}$	$V_{DD} \leq 16V$ , $T_A = -40..85^\circ C$ , $T_{OP} = T_{OP2}$	—	8.1	11.7	$\mu A$
Step response time <sup>(2)</sup>	$t_{RESP}$	Fast Mode, $B_{OP} = 1mT$ , $B_{RP} = -1mT$ , square wave magnetic field with $B > \pm 4mT$ , $t_{RISE} = t_{FALL} \leq 5\mu s$	15	40	65	$\mu s$
Signal bandwidth <sup>(2,6)</sup>	BW	Fast Mode, $B_{OP} = 1mT$ , $B_{RP} = -1mT$ , sine wave magnetic field with amplitude $5mT$	6	8	—	kHz
Peak supply current <sup>(2)</sup>	$I_{DDPEAK}$	For peak duration $\geq 5\mu s$	—	2.9	3.6	mA
Fast Mode supply current	$I_{DDFAST}$		2.2	2.9	3.5	mA
Fast Mode fail supply current	$I_{DDFAIL}$		0.1	0.3	0.6	mA

Reverse supply current	$I_{DDREV}$	$V_{DD} = -16V$	-1	—	—	mA
Thermal Protection Activation	$T_{PROT}$		—	185 <sup>(7)</sup>	—	°C
Thermal Protection Release	$T_{REL}$		—	175 <sup>(7)</sup>	—	°C
UA package thermal resistance	$R_{THJA}$	Single layer PCB, JEDEC standard test boards, still air (LFPM=0)	—	200	—	°C/W
SE package thermal resistance	$R_{THJA}$	Single layer PCB, JEDEC standard test boards, still air (LFPM=0)	—	300	—	°C/W

- 1 Unless otherwise specified the typical values are defined at  $T_A = +25^\circ C$  and  $V_{DD} = 12V$
- 2 Guaranteed by design and verified by characterization, not production tested
- 3 The Power-On Time represents the time from reaching  $V_{DD} = 3.3V$  to the first refresh of the output state.
- 4 Power-On Slew Rate is not critical for the proper device start-up.
- 5  $R_{PU}$  and  $V_{PU}$  are respectively the external pull-up resistor and pull-up power supply
- 6 OUT switching should track magnetic field frequency without missing pulses
- 7  $T_{PROT}$  and  $T_{REL}$  are the corresponding junction temperature values
- 8 Guaranteed by correlation with production test at  $T_A=150^\circ C$  and verified by characterization
- 9 Average current consumption for  $\mu$ -Power Mode with diagnostic On

$$I_{DDAVG} = \frac{I_{DDACT} * t_{ACT} * (1 + R_{TOL}/100) + I_{DDSTBY} * (T_{OP} - t_{ACT} * (1 + R_{TOL}/100))}{T_{OP}}$$

Where  $t_{act}$  and  $T_{OP}$  are always typical values. The maximum  $I_{DDACT}$ ,  $I_{DDSTBY}$  and  $R_{TOL}$  spec values should be used for the maximum  $I_{DDAVG}$  calculation.





## 8 Version specific parameters

### 8.1 MLX92292LSE-AAA-000-RE/MLX92292LUA-AAA-000-BU/MLX92292LDC-AAA-000-RE

All MLX92292 devices are unlocked and can be tuned with the Melexis PTC04 programmer.

DC Operating Parameters  $V_{DD} = 3.3V$  to  $18V$ ,  $T_A = -40^{\circ}C$  to  $150^{\circ}C$  (unless otherwise specified)

Parameter	Symbol	Test Conditions	Min	Typ <sup>(1)</sup>	Max	
Operating Point programming range	B <sub>OP</sub>	$V_{DD} = 12V, T_A = 25^{\circ}C$	-90	—	90	mT
Release Point programming range	B <sub>RP</sub>	$V_{DD} = 12V, T_A = 25^{\circ}C$	-90	—	90	mT
Operating Point magnitude programming <sup>(2, 3)</sup>	B <sub>OP</sub>		—	12	—	bit
Release Point magnitude programming <sup>(2, 3)</sup>	B <sub>RP</sub>		—	12	—	bit
Operating Point polarity selection	B <sub>OP</sub>		—	1	—	bit
Release Point polarity selection	B <sub>RP</sub>		—	1	—	bit
Direct or inverted output selection	—		—	1	—	bit
Factory pre-programmed Operating Point, Latch	B <sub>OP</sub>	$V_{DD} = 12V, T_A = 25^{\circ}C$ , programming target 25mT	22	25	28	mT
Factory pre-programmed Release Point, Latch	B <sub>RP</sub>	$V_{DD} = 12V, T_A = 25^{\circ}C$ , programming target -25mT	-28	-25	-22	mT
Temperature Coefficient programming range <sup>(4,5,6)</sup>	TC	$V_{DD} = 12V$ , Latch with B <sub>OP</sub> = 25mT, B <sub>RP</sub> = -25mT	-2400		0	ppm/°C
Temperature Coefficient selection	TC		—	5	—	bit

IMC	Safe message	Operating period, ms	Diagnostic period in Fail Safe state, ms	“Output Ticking” duration, μs	“Output Ticking” repetition period, ms
No	TickMsg	45	-	128	45

<sup>1</sup> Unless otherwise specified the typical values are defined at  $T_A = +25^{\circ}C$  and  $V_{DD} = 12V$

<sup>2</sup> The programming step is <0.5% of the programmed BOP or BRP value for  $|BOP|$  or  $|BRP| \geq 6mT$  and <0.02mT for  $|BOP|$  or  $|BRP| \leq 6mT$  at  $T_A = +25^{\circ}C$

<sup>3</sup> Very low hysteresis magnitude ( $BOP - BRP < 1mT$ ) could lead to output toggling due to noise and mechanical looseness in the magnetic system.

<sup>4</sup> The Temperature Coefficient is calculated using following formula:

$$TC = \frac{B_{XPTA2} - B_{XPTA1}}{B_{XPTA1} * (T_{A2} - T_{A1})} * 10^6, ppm/^{\circ}C$$

where:

$$T_{A1} = 25^{\circ}C, T_{A2} = 150^{\circ}C,$$

In case of magnetic Latch application:  $B_{XPTA1} (B_{XPTA2}) = B_{OP} - B_{RP}$  at  $T_{A1} (T_{A2})$

In case of magnetic Switch application:  $B_{XPTA1} (B_{XPTA2}) = B_{OP}$  or  $B_{RP}$  at  $T_{A1} (T_{A2})$

<sup>5</sup> The factory pre-programmed target TC value is 0ppm/°C.

<sup>6</sup> TC target values

# MLX92292/MLX92291/MLX92271

## 3-wire $\mu$ Power programmable ASIL B capable Hall Effect Latch/Switch

### Datasheet

## 8.2 MLX92292LSE-AAA-200-RE

All MLX92292 devices are unlocked and can be tuned with the Melexis PTC04 programmer.

DC Operating Parameters  $V_{DD} = 3.3V$  to  $18V$ ,  $T_A = -40^\circ C$  to  $150^\circ C$  (unless otherwise specified)

Parameter	Symbol	Test Conditions	Min	Typ <sup>(1)</sup>	Max	
Operating Point programming range	BOP	$V_{DD} = 12V$ , $T_A = 25^\circ C$	-40	—	40	mT
Release Point programming range	BRP	$V_{DD} = 12V$ , $T_A = 25^\circ C$	-40	—	40	mT
Operating Point magnitude programming <sup>(2,3)</sup>	BOP		—	12	—	bit
Release Point magnitude programming <sup>(2,3)</sup>	BRP		—	12	—	bit
Operating Point polarity selection	BOP		—	1	—	bit
Release Point polarity selection	BRP		—	1	—	bit
Direct or inverted output selection	—		—	1	—	bit
Factory pre-programmed Operating Point, Latch	BOP	$V_{DD} = 12V$ , $T_A = 25^\circ C$ , programming target 20mT	17	20	23	mT
Factory pre-programmed Release Point, Latch	BRP	$V_{DD} = 12V$ , $T_A = 25^\circ C$ , programming target -20mT	-23	-20	-17	mT
Temperature Coefficient programming range <sup>(4,5,6)</sup>	TC	$V_{DD} = 12V$ , Latch with $B_{OP} = 20mT$ , $B_{RP} = -20mT$	-2400		0	ppm/ $^\circ C$
Temperature Coefficient selection	TC		—	5	—	bit

IMC	Safe message	Operating period, ms	Diagnostic period in Fail Safe state, ms	“Output Ticking” duration, $\mu s$	“Output Ticking” repetition period, ms
Yes	TickMsg	45	-	128	45

<sup>1</sup> Unless otherwise specified the typical values are defined at  $T_A = +25^\circ C$  and  $V_{DD} = 12V$

<sup>2</sup> The programming step is  $<0.5\%$  of the programmed BOP or BRP value for  $|BOP|$  or  $|BRP| \geq 6mT$  and  $<0.02mT$  for  $|BOP|$  or  $|BRP| \leq 6mT$  at  $T_A = +25^\circ C$

<sup>3</sup> Very low hysteresis magnitude ( $BOP - BRP < 1mT$ ) could lead to output toggling due to noise and mechanical looseness in the magnetic system.

<sup>4</sup> The Temperature Coefficient is calculated using following formula:

$$TC = \frac{B_{XPTA2} - B_{XPTA1}}{B_{XPTA1} * (T_{A2} - T_{A1})} * 10^6, ppm/^\circ C$$

where:

$$T_{A1} = 25^\circ C, T_{A2} = 150^\circ C,$$

In case of magnetic Latch application:  $B_{XPTA1} (B_{XPTA2}) = B_{OP} - B_{RP}$  at  $T_{A1} (T_{A2})$

In case of magnetic Switch application:  $B_{XPTA1} (B_{XPTA2}) = B_{OP}$  or  $B_{RP}$  at  $T_{A1} (T_{A2})$

<sup>5</sup> The factory pre-programmed target TC value is  $0ppm/^\circ C$ .

<sup>6</sup> TC target values

# MLX92292/MLX92291/MLX92271

3-wire  $\mu$ Power programmable ASIL B capable Hall Effect Latch/Switch

Datasheet



## 8.3 MLX92292LSE-AAA-001-RE

DC Operating Parameters  $V_{DD} = 3.3$  to  $18V$ ,  $T_A = -40^\circ C$  to  $150^\circ C$

Test Condition	Operating Point $B_{OP}$ (mT)			Release Point $B_{RP}$ (mT)			TC (ppm/ $^\circ C$ )	Output behaviour	Active Pole
	Min	Typ <sup>(1)</sup>	Max	Min	Typ <sup>(1)</sup>	Max			
$T_A = -40^\circ C$	8.7	11.0	13.5	7.2	9.3	11.7	-1100 <sup>(2)</sup>	Inverted switch	South pole
$T_A = 25^\circ C$	8.6	10.0	11.4	7.2	8.5	9.8			
$T_A = 150^\circ C$	6.7	8.6	10.7	5.6	7.4	9.4			

IMC	Safe message	Operating period, ms	Diagnostic period in Fail Safe state, ms	“Output Ticking” duration, $\mu s$	“Output Ticking” repetition period, ms
No	uNoDiag	0.16	-	-	-

## 8.4 MLX92291LSE-AAA-002-RE

DC Operating Parameters  $V_{DD} = 3.3$  to  $18V$ ,  $T_A = -40^\circ C$  to  $150^\circ C$

Test Condition	Operating Point $B_{OP}$ (mT) <sup>(3)</sup>			Release Point $B_{RP}$ (mT) <sup>(3)</sup>			TC (ppm/ $^\circ C$ )	Output behaviour	Active Pole
	Min	Typ <sup>(1)</sup>	Max	Min	Typ <sup>(1)</sup>	Max			
$T_A = -40^\circ C$	11.5	14.5	17.6	6.6	9.1	11.8	-1100 <sup>(2)</sup>	Direct switch	South pole
$T_A = 25^\circ C$	11.7	13.5	15.4	6.9	8.5	10.1			
$T_A = 150^\circ C$	8.7	11.6	14.9	4.9	7.3	10.0			

IMC	Safe message	Operating period, ms	Diagnostic period in Fail Safe state, ms	“Output Ticking” duration, $\mu s$	“Output Ticking” repetition period, ms
No	TickMsg	10	-	128	10

## 8.5 MLX92291LSE-AAA-005-RE

DC Operating Parameters  $V_{DD} = 3.3$  to  $18V$ ,  $T_A = -40^\circ C$  to  $150^\circ C$

Test Condition	Operating Point $B_{OP}$ (mT)			Release Point $B_{RP}$ (mT)			TC (ppm/ $^\circ C$ )	Output behaviour	Active Pole
	Min	Typ <sup>(1)</sup>	Max	Min	Typ <sup>(1)</sup>	Max			
$T_A = -40^\circ C$	-8.5	-6.4	-4.4	-9.7	-7.5	-5.4	-1100 <sup>(2)</sup>	Direct switch	North pole
$T_A = 25^\circ C$	-7.2	-6	-4.9	-8.2	-7	-5.8			
$T_A = 150^\circ C$	-7.2	-5.2	-3.3	-8.2	-6	-4			

IMC	Safe message	Operating period, ms	Diagnostic period in Fail Safe state, ms	“Output Ticking” duration, $\mu s$	“Output Ticking” repetition period, ms
No	OutOnMsg	50	-	-	-

<sup>1</sup> Unless otherwise specified the typical values are defined at  $T_A = +25^\circ C$  and  $V_{DD} = 12V$ . Melexis production testing is limited to version specific parameters only.

<sup>2</sup> Typical TC programmed. The Temperature Coefficient is calculated using formula from section 8

<sup>3</sup> Final magnetic parameters will be covered in the PPAP documentation set, the table below is based on theoretical calculations

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## 8.6 MLX92291LSE-AAA-006-RE

DC Operating Parameters  $V_{DD} = 3.3$  to  $18V$ ,  $T_A = -40^\circ C$  to  $150^\circ C$

Test Condition	Operating Point $B_{OP}$ (mT)			Release Point $B_{RP}$ (mT)			TC (ppm/ $^\circ C$ )	Output behaviour	Active Pole
	Min	Typ <sup>(1)</sup>	Max	Min	Typ <sup>(1)</sup>	Max			
$T_A = -40^\circ C$	-6.8	-4.8	-2.9	-7.9	-5.9	-3.9	-1000 <sup>(2)</sup>	Inverted switch	North pole
$T_A = 25^\circ C$	-5.6	-4.5	-3.4	-6.6	-5.5	-4.4			
$T_A = 150^\circ C$	-5.8	-3.9	-2.1	-6.8	-4.8	-2.9			

IMC	Safe message	Operating period, ms	Diagnostic period in Fail Safe state, ms	“Output Ticking” duration, $\mu s$	“Output Ticking” repetition period, ms
No	uNoDiag	60	-	-	-

## 8.7 MLX92291LSE-AAA-007-RE

DC Operating Parameters  $V_{DD} = 3.3$  to  $18V$ ,  $T_A = -40^\circ C$  to  $150^\circ C$

Test Condition	Operating Point $B_{OP}$ (mT) <sup>(3)</sup>			Release Point $B_{RP}$ (mT) <sup>(3)</sup>			TC (ppm/ $^\circ C$ )	Output behaviour	Active Pole
	Min	Typ <sup>(1)</sup>	Max	Min	Typ <sup>(1)</sup>	Max			
$T_A = -40^\circ C$	7.1	9.6	12.3	5.1	7.5	10.0	-1000 <sup>(2)</sup>	Direct switch	South pole
$T_A = 25^\circ C$	7.4	9.0	10.6	5.5	7.0	8.6			
$T_A = 150^\circ C$	5.3	7.8	10.5	3.7	6.0	8.5			

IMC	Safe message	Operating period, ms	Diagnostic period in Fail Safe state, ms	“Output Ticking” duration, $\mu s$	“Output Ticking” repetition period, ms
No	TickMsg	10	-	128	10

## 8.8 MLX92291LSE-AAA-008-RE

DC Operating Parameters  $V_{DD} = 3.3$  to  $18V$ ,  $T_A = -40^\circ C$  to  $150^\circ C$

Test Condition	Operating Point $B_{OP}$ (mT) <sup>(3)</sup>			Release Point $B_{RP}$ (mT) <sup>(3)</sup>			TC (ppm/ $^\circ C$ )	Output behaviour	Active Pole
	Min	Typ <sup>(1)</sup>	Max	Min	Typ <sup>(1)</sup>	Max			
$T_A = -40^\circ C$	-21.4	-18.1	-15	-22.6	-19.1	-16	-1100 <sup>(2)</sup>	Direct switch	North pole
$T_A = 25^\circ C$	-18.7	-16.85	-15.1	-19.8	-17.85	-16			
$T_A = 150^\circ C$	-18.1	-14.5	-11.4	-19.1	-15.4	-12.1			

IMC	Safe message	Operating period, ms	Diagnostic period in Fail Safe state, ms	“Output Ticking” duration, $\mu s$	“Output Ticking” repetition period, ms
No	uNoDiag	44	-	-	-

<sup>1</sup> Unless otherwise specified the typical values are defined at  $T_A = +25^\circ C$  and  $V_{DD} = 12V$ . Melexis production testing is limited to version specific parameters only.

<sup>2</sup> Typical TC programmed. The Temperature Coefficient is calculated using formula from section 8

<sup>3</sup> Final magnetic parameters will be covered in the PPAP documentation set, the table below is based on theoretical calculations

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## 8.9 MLX92291LSE-AAA-009-RE

DC Operating Parameters  $V_{DD} = 3.3$  to  $18V$ ,  $T_A = -40^\circ C$  to  $150^\circ C$

Test Condition	Operating Point $B_{OP}$ (mT)			Release Point $B_{RP}$ (mT)			TC (ppm/ $^\circ C$ )	Output behaviour	Active Pole
	Min	Typ <sup>(1)</sup>	Max	Min	Typ <sup>(1)</sup>	Max			
$T_A = -40^\circ C$	-6.4	-4.5	-2.6	-7.5	-5.5	-3.6	0 <sup>(2)</sup>	Inverted switch	North pole
$T_A = 25^\circ C$	-5.6	-4.5	-3.4	-6.6	-5.5	-4.4			
$T_A = 150^\circ C$	-6.6	-4.5	-2.5	-7.7	-5.5	-3.4			

IMC	Safe message	Operating period, ms	Diagnostic period in Fail Safe state, ms	“Output Ticking” duration, $\mu s$	“Output Ticking” repetition period, ms
No	uNoDiag	10	-	-	-

## 8.10 MLX92291LSE-AAA-010-RE

DC Operating Parameters  $V_{DD} = 3.3$  to  $18V$ ,  $T_A = -40^\circ C$  to  $150^\circ C$

Test Condition	Operating Point $B_{OP}$ (mT) <sup>(3)</sup>			Release Point $B_{RP}$ (mT) <sup>(3)</sup>			TC (ppm/ $^\circ C$ )	Output behaviour	Active Pole
	Min	Typ <sup>(1)</sup>	Max	Min	Typ <sup>(1)</sup>	Max			
$T_A = -40^\circ C$	5.2	6.9	8.6	3.1	4.6	6.2	-1100 <sup>(2)</sup>	Direct switch	South pole
$T_A = 25^\circ C$	5.2	6.4	7.6	3.2	4.3	5.4			
$T_A = 150^\circ C$	3.8	5.5	7.4	2.2	3.7	5.3			

IMC	Safe message	Operating period, ms	Diagnostic period in Fail Safe state, ms	“Output Ticking” duration, $\mu s$	“Output Ticking” repetition period, ms
No	TickMsg	10	-	128	10

## 8.11 MLX92291LSE-AAA-011-RE

DC Operating Parameters  $V_{DD} = 3.3$  to  $18V$ ,  $T_A = -40^\circ C$  to  $150^\circ C$

Test Condition	Operating Point $B_{OP}$ (mT) <sup>(3)</sup>			Release Point $B_{RP}$ (mT) <sup>(3)</sup>			TC (ppm/ $^\circ C$ )	Output behaviour	Active Pole
	Min	Typ <sup>(1)</sup>	Max	Min	Typ <sup>(1)</sup>	Max			
$T_A = -40^\circ C$	-26.3	-22.3	-18.5	-28.7	-24.4	-20.4	-999 <sup>(2)</sup>	Direct switch	North pole
$T_A = 25^\circ C$	-23.3	-20.9	-18.6	-25.4	-22.9	-20.5			
$T_A = 150^\circ C$	-22.8	-18.3	-14.3	-24.8	-20.0	-15.8			

IMC	Safe message	Operating period, ms	Diagnostic period in Fail Safe state, ms	“Output Ticking” duration, $\mu s$	“Output Ticking” repetition period, ms
No	TickOnMsg	0.86	-	128	1.72

<sup>1</sup> Unless otherwise specified the typical values are defined at  $T_A = +25^\circ C$  and  $V_{DD} = 12V$ . Melexis production testing is limited to version specific parameters only.

<sup>2</sup> Typical TC programmed. The Temperature Coefficient is calculated using formula from section 8.

<sup>3</sup> Final magnetic parameters will be covered in the PPAP documentation set, the table below is based on theoretical calculations

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## 8.12 MLX92291LSE-AAA-012-RE

DC Operating Parameters  $V_{DD} = 3.3$  to  $18V$ ,  $T_A = -40^\circ C$  to  $150^\circ C$

Test Condition	Operating Point $B_{OP}$ (mT) <sup>(3)</sup>			Release Point $B_{RP}$ (mT) <sup>(3)</sup>			TC (ppm/ $^\circ C$ )	Output behaviour	Active Pole
	Min	Typ <sup>(1)</sup>	Max	Min	Typ <sup>(1)</sup>	Max			
$T_A = -40^\circ C$	3.9	5.9	7.9	2.9	4.8	6.8	-1000 <sup>(2)</sup>	Direct switch	South pole
$T_A = 25^\circ C$	4.4	5.5	6.6	3.4	4.5	5.6			
$T_A = 150^\circ C$	2.9	4.8	6.8	2.1	3.9	5.8			

IMC	Safe message	Operating period, ms	Diagnostic period in Fail Safe state, ms	“Output Ticking” duration, $\mu s$	“Output Ticking” repetition period, ms
No	uNoDiag	60	-	-	-

## 8.13 MLX92291LSE-AAA-013-RE

DC Operating Parameters  $V_{DD} = 3.3$  to  $18V$ ,  $T_A = -40^\circ C$  to  $150^\circ C$

Test Condition	Operating Point $B_{OP}$ (mT) <sup>(3)</sup>			Release Point $B_{RP}$ (mT) <sup>(3)</sup>			TC (ppm/ $^\circ C$ )	Output behaviour	Active Pole
	Min	Typ <sup>(1)</sup>	Max	Min	Typ <sup>(1)</sup>	Max			
$T_A = -40^\circ C$	24.3	28.7	33.6	22.2	26.4	31.0	-1100 <sup>(2)</sup>	Direct switch	South pole
$T_A = 25^\circ C$	24.2	26.8	29.6	22.1	24.6	27.2			
$T_A = 105^\circ C$ <sup>(4)</sup>	20.3	24.2	29.0	18.5	22.4	26.8			
$T_A = 150^\circ C$	18.4	23.1	28.5	16.8	21.2	26.2			

IMC	Safe message	Operating period, ms	Diagnostic period in Fail Safe state, ms	“Output Ticking” duration, $\mu s$	“Output Ticking” repetition period, ms
No	uNoDiag	1	-	-	-

## 8.14 MLX92291LSE-AAA-200-RE

DC Operating Parameters  $V_{DD} = 3.3$  to  $18V$ ,  $T_A = -40^\circ C$  to  $150^\circ C$

Test Condition	Operating Point $B_{OP}$ (mT)			Release Point $B_{RP}$ (mT)			TC (ppm/ $^\circ C$ )	Output behaviour	Active Pole
	Min	Typ <sup>(1)</sup>	Max	Min	Typ <sup>(1)</sup>	Max			
$T_A = -40^\circ C$	7.6	10.5	13.6	5.6	8.1	11	-2200 <sup>(2)</sup>	Inverted switch	South pole
$T_A = 25^\circ C$	7	9	11	5.1	7	8.9			
$T_A = 150^\circ C$	4.5	6.6	8.9	3.2	5.2	7.2			

IMC	Safe message	Operating period, ms	Diagnostic period in Fail Safe state, ms	“Output Ticking” duration, $\mu s$	“Output Ticking” repetition period, ms
Yes	FlddMsg	-	2	-	-

<sup>1</sup> Unless otherwise specified the typical values are defined at  $T_A = +25^\circ C$  and  $V_{DD} = 12V$ . Melexis production testing is limited to version specific parameters only.

<sup>2</sup> Typical TC programmed. The Temperature Coefficient is calculated using formula from section 8.

<sup>3</sup> Final magnetic parameters will be covered in the PPAP documentation set, the table below is based on theoretical calculations

<sup>4</sup> Row “ $T_A = 105^\circ C$ ” is based on theoretical calculations only, not production tested.

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## 8.15 MLX92291LSE-AAA-201-RE

DC Operating Parameters  $V_{DD} = 3.3$  to  $18V$ ,  $T_A = -40^\circ C$  to  $150^\circ C$

Test Condition	Operating Point $B_{OP}$ (mT) <sup>(3)</sup>			Release Point $B_{RP}$ (mT) <sup>(3)</sup>			TC (ppm/ $^\circ C$ )	Output behaviour	Active Pole
	Min	Typ <sup>(1)</sup>	Max	Min	Typ <sup>(1)</sup>	Max			
$T_A = -40^\circ C$	7.0	9.6	12.5	6.7	9.3	12.1	-1100 <sup>(2)</sup>	Inverted switch	South pole
$T_A = 25^\circ C$	7.0	8.8	10.7	6.7	8.5	10.4			
$T_A = 150^\circ C$	5.4	7.7	10.2	5.2	7.4	9.9			

IMC	Safe message	Operating period, ms	Diagnostic period in Fail Safe state, ms	“Output Ticking” duration, $\mu s$	“Output Ticking” repetition period, ms
Yes	uNoDiag	45	-	-	-

## 8.16 MLX92291LSE-AAA-202-RE

DC Operating Parameters  $V_{DD} = 3.3$  to  $18V$ ,  $T_A = -40^\circ C$  to  $150^\circ C$

Test Condition	Operating Point $B_{OP}$ (mT)			Release Point $B_{RP}$ (mT)			TC (ppm/ $^\circ C$ )	Output behaviour	Active Pole
	Min	Typ <sup>(1)</sup>	Max	Min	Typ <sup>(1)</sup>	Max			
$T_A = -40^\circ C$	3.8	5.9	8.2	2.8	4.8	7.0	-1100 <sup>(2)</sup>	Inverted switch	South pole
$T_A = 25^\circ C$	3.8	5.4	7.0	2.9	4.4	6.0			
$T_A = 150^\circ C$	2.8	4.7	6.8	2.0	3.9	5.8			

IMC	Safe message	Operating period, ms	Diagnostic period in Fail Safe state, ms	“Output Ticking” duration, $\mu s$	“Output Ticking” repetition period, ms
Yes	uNoDiag	10	-	-	-

## 8.17 MLX92291LSE-AAA-203-RE

DC Operating Parameters  $V_{DD} = 3.3$  to  $18V$ ,  $T_A = -40^\circ C$  to  $150^\circ C$

Test Condition	Operating Point $B_{OP}$ (mT) <sup>(3)</sup>			Release Point $B_{RP}$ (mT) <sup>(3)</sup>			TC (ppm/ $^\circ C$ )	Output behaviour	Active Pole
	Min	Typ <sup>(1)</sup>	Max	Min	Typ <sup>(1)</sup>	Max			
$T_A = -40^\circ C$	-5.9	-3.6	-1.3	-7.0	-4.6	-2.3	-1100 <sup>(2)</sup>	Direct switch	North pole
$T_A = 25^\circ C$	-4.8	-3.33	-1.8	-5.9	-4.33	-2.8			
$T_A = 150^\circ C$	-5.1	-2.9	-0.7	-6.0	-3.7	-1.6			

IMC	Safe message	Operating period, ms	Diagnostic period in Fail Safe state, ms	“Output Ticking” duration, $\mu s$	“Output Ticking” repetition period, ms
Yes	uNoDiag	44	-	-	-

<sup>1</sup> Unless otherwise specified the typical values are defined at  $T_A = +25^\circ C$  and  $V_{DD} = 12V$ . Melexis production testing is limited to version specific parameters only.

<sup>2</sup> Typical TC programmed. The Temperature Coefficient is calculated using formula from section 8

<sup>3</sup> Final magnetic parameters will be covered in the PPAP documentation set, the table below is based on theoretical calculations

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## 8.18 MLX92291LSE-AAA-204-RE

DC Operating Parameters  $V_{DD} = 3.3$  to  $18V$ ,  $T_A = -40^\circ C$  to  $150^\circ C$

Test Condition	Operating Point $B_{OP}$ (mT) <sup>(3)</sup>			Release Point $B_{RP}$ (mT) <sup>(3)</sup>			TC (ppm/ $^\circ C$ )	Output behaviour	Active Pole
	Min	Typ <sup>(1)</sup>	Max	Min	Typ <sup>(1)</sup>	Max			
$T_A = -40^\circ C$	-23.9	-19.9	-16.3	-24.4	-20.5	-16.8	-1100 <sup>(2)</sup>	Direct switch	North pole
$T_A = 25^\circ C$	-20.9	-18.6	-16.4	-21.5	-19.1	-16.8			
$T_A = 150^\circ C$	-20.2	-16.0	-12.3	-20.7	-16.5	-12.7			

IMC	Safe message	Operating period, ms	Diagnostic period in Fail Safe state, ms	“Output Ticking” duration, $\mu s$	“Output Ticking” repetition period, ms
Yes	OutOnMsg	50	-	-	-

## 8.19 MLX92291LSE-AAA-207-RE

DC Operating Parameters  $V_{DD} = 3.3$  to  $18V$ ,  $T_A = -40^\circ C$  to  $150^\circ C$

Test Condition	Operating Point $B_{OP}$ (mT) <sup>(3)</sup>			Release Point $B_{RP}$ (mT) <sup>(3)</sup>			TC (ppm/ $^\circ C$ )	Output behaviour	Active Pole
	Min	Typ <sup>(1)</sup>	Max	Min	Typ <sup>(1)</sup>	Max			
$T_A = -40^\circ C$	0.4	2.8	5.3	-0.5	1.9	4.3	-2000 <sup>(2)</sup>	Direct switch	South pole
$T_A = 25^\circ C$	1.0	2.5	4.0	0.2	1.7	3.2			
$T_A = 150^\circ C$	-0.1	1.9	3.9	-0.7	1.3	3.3			

IMC	Safe message	Operating period, ms	Diagnostic period in Fail Safe state, ms	“Output Ticking” duration, $\mu s$	“Output Ticking” repetition period, ms
Yes	uNoDiag	6.8	-	-	-

## 8.20 MLX92291LSE-AAA-208-RE

DC Operating Parameters  $V_{DD} = 3.3$  to  $18V$ ,  $T_A = -40^\circ C$  to  $150^\circ C$

Test Condition	Operating Point $B_{OP}$ (mT) <sup>(3)</sup>			Release Point $B_{RP}$ (mT) <sup>(3)</sup>			TC (ppm/ $^\circ C$ )	Output behaviour	Active Pole
	Min	Typ <sup>(1)</sup>	Max	Min	Typ <sup>(1)</sup>	Max			
$T_A = -40^\circ C$	5.2	7.79	10.5	4.4	7.0	9.7	0 <sup>(2)</sup>	Direct switch	South pole
$T_A = 25^\circ C$	6.0	7.79	9.6	5.2	7.0	8.8			
$T_A = 150^\circ C$	4.9	7.79	10.9	4.2	7.0	10.0			

IMC	Safe message	Operating period, ms	Diagnostic period in Fail Safe state, ms	“Output Ticking” duration, $\mu s$	“Output Ticking” repetition period, ms
Yes	StbyX2Msg	10	20	-	-

<sup>1</sup> Unless otherwise specified the typical values are defined at  $T_A = +25^\circ C$  and  $V_{DD} = 12V$ . Melexis production testing is limited to version specific parameters only.

<sup>2</sup> Typical TC programmed. The Temperature Coefficient is calculated using formula from section 8

<sup>3</sup> Final magnetic parameters will be covered in the PPAP documentation set, the table below is based on theoretical calculations



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## 8.21 MLX92271LSE-AAA-001-RE

DC Operating Parameters  $V_{DD} = 3.3$  to  $18V$ ,  $T_A = -40^\circ C$  to  $150^\circ C$

Test Condition	Operating Point $B_{OP}$ (mT) <sup>(3)</sup>			Release Point $B_{RP}$ (mT) <sup>(3)</sup>			TC (ppm/ $^\circ C$ )	Output behaviour	Active Pole
	Min	Typ <sup>(1)</sup>	Max	Min	Typ <sup>(1)</sup>	Max			
$T_A = -40^\circ C$	-0.9	0.4	1.9	-1.9	-0.4	0.9	0 <sup>(2)</sup>	Latch	South pole
$T_A = 25^\circ C$	-0.9	0.4	1.9	-1.9	-0.4	0.9			
$T_A = 150^\circ C$	-0.9	0.4	1.9	-1.9	-0.4	0.9			

IMC	Safe message	Operating period, ms	Diagnostic period in Fail Safe state, ms	“Output Ticking” duration, $\mu s$	“Output Ticking” repetition period, ms
No	FNoDiag	-	-	-	-

## 8.22 MLX92271LSE-AAA-014-RE

DC Operating Parameters  $V_{DD} = 3.3$  to  $18V$ ,  $T_A = -40^\circ C$  to  $150^\circ C$

Test Condition	Operating Point $B_{OP}$ (mT) <sup>(3)</sup>			Release Point $B_{RP}$ (mT) <sup>(3)</sup>			TC (ppm/ $^\circ C$ )	Output behaviour	Active Pole
	Min	Typ <sup>(1)</sup>	Max	Min	Typ <sup>(1)</sup>	Max			
$T_A = -40^\circ C$	-0.1	2.1	4.5	-4.5	-2.1	0.1	-1100 <sup>(2)</sup>	Latch	South pole
$T_A = 25^\circ C$	0.5	2.0	3.5	-3.5	-2.0	-0.5			
$T_A = 150^\circ C$	-0.4	1.7	3.9	-3.9	-1.7	0.4			

IMC	Safe message	Operating period, ms	Diagnostic period in Fail Safe state, ms	“Output Ticking” duration, $\mu s$	“Output Ticking” repetition period, ms
No	FNoDiag	-	-	-	-

## 8.23 MLX92271LSE-AAA-015-RE

DC Operating Parameters  $V_{DD} = 3.3$  to  $18V$ ,  $T_A = -40^\circ C$  to  $150^\circ C$

Test Condition	Operating Point $B_{OP}$ (mT) <sup>(3)</sup>			Release Point $B_{RP}$ (mT) <sup>(3)</sup>			TC (ppm/ $^\circ C$ )	Output behaviour	Active Pole
	Min	Typ <sup>(1)</sup>	Max	Min	Typ <sup>(1)</sup>	Max			
$T_A = -40^\circ C$	-1.8	-0.4	1.0	-1.0	0.4	1.8	0 <sup>(2)</sup>	Latch	North pole
$T_A = 25^\circ C$	-1.7	-0.4	0.9	-0.9	0.4	1.7			
$T_A = 150^\circ C$	-2.1	-0.4	1.3	-1.3	0.4	2.1			

IMC	Safe message	Operating period, ms	Diagnostic period in Fail Safe state, ms	“Output Ticking” duration, $\mu s$	“Output Ticking” repetition period, ms
No	uNoDiag	60	-	-	-

<sup>1</sup> Unless otherwise specified the typical values are defined at  $T_A = +25^\circ C$  and  $V_{DD} = 12V$ . Melexis production testing is limited to version specific parameters only.

<sup>2</sup> Typical TC programmed. The Temperature Coefficient is calculated using formula from section 8.

<sup>3</sup> Final magnetic parameters will be covered in the PPAP documentation set, the table below is based on theoretical calculations.

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## 8.24 MLX92271LSE-AAA-016-RE

DC Operating Parameters  $V_{DD} = 3.3$  to  $18V$ ,  $T_A = -40^\circ C$  to  $150^\circ C$

Test Condition	Operating Point $B_{OP}$ (mT) <sup>(3)</sup>			Release Point $B_{RP}$ (mT) <sup>(3)</sup>			TC (ppm/ $^\circ C$ )	Output behaviour	Active Pole
	Min	Typ <sup>(1)</sup>	Max	Min	Typ <sup>(1)</sup>	Max			
$T_A = -40^\circ C$	2.3	3.9	5.5	-5.5	-3.9	-2.3	-1100 <sup>(2)</sup>	Latch	South pole
$T_A = 25^\circ C$	2.3	3.6	4.9	-4.9	-3.6	-2.3			
$T_A = 150^\circ C$	1.5	3.1	4.8	-4.8	-3.1	-1.5			

IMC	Safe message	Operating period, ms	Diagnostic period in Fail Safe state, ms	“Output Ticking” duration, $\mu s$	“Output Ticking” repetition period, ms
No	uNoDiag	45	-	-	-

## 8.25 MLX92271LSE-AAA-017-RE

DC Operating Parameters  $V_{DD} = 3.3$  to  $18V$ ,  $T_A = -40^\circ C$  to  $150^\circ C$

Test Condition	Operating Point $B_{OP}$ (mT) <sup>(3)</sup>			Release Point $B_{RP}$ (mT) <sup>(3)</sup>			TC (ppm/ $^\circ C$ )	Output behaviour	Active Pole
	Min	Typ <sup>(1)</sup>	Max	Min	Typ <sup>(1)</sup>	Max			
$T_A = -40^\circ C$	2.3	3.9	5.5	-5.5	-3.9	-2.3	-1100 <sup>(2)</sup>	Latch	South pole
$T_A = 25^\circ C$	2.3	3.6	4.9	-4.9	-3.6	-2.3			
$T_A = 150^\circ C$	1.5	3.1	4.8	-4.8	-3.1	-1.5			

IMC	Safe message	Operating period, ms	Diagnostic period in Fail Safe state, ms	“Output Ticking” duration, $\mu s$	“Output Ticking” repetition period, ms
No	uNoDiag	25	-	-	-

## 8.26 MLX92271LSE-AAA-205-RE

DC Operating Parameters  $V_{DD} = 3.3$  to  $18V$ ,  $T_A = -40^\circ C$  to  $150^\circ C$

Test Condition	Operating Point $B_{OP}$ (mT)			Release Point $B_{RP}$ (mT)			TC (ppm/ $^\circ C$ )	Output behaviour	Active Pole
	Min	Typ <sup>(1)</sup>	Max	Min	Typ <sup>(1)</sup>	Max			
$T_A = -40^\circ C$	-0.9	1.5	3.9	-3.9	-1.5	0.9	0 <sup>(2)</sup>	Latch	South pole
$T_A = 25^\circ C$	-0.2	1.5	3.2	-3.2	-1.5	0.2			
$T_A = 150^\circ C$	-0.9	1.5	4.0	-4.0	-1.5	0.9			

IMC	Safe message	Operating period, ms	Diagnostic period in Fail Safe state, ms	“Output Ticking” duration, $\mu s$	“Output Ticking” repetition period, ms
Yes	FNoDiag	-	-	-	-

<sup>1</sup> Unless otherwise specified the typical values are defined at  $T_A = +25^\circ C$  and  $V_{DD} = 12V$ . Melexis production testing is limited to version specific parameters only.

<sup>2</sup> Typical TC programmed. The Temperature Coefficient is calculated using formula from section 8.

<sup>3</sup> Final magnetic parameters will be covered in the PPAP documentation set, the table below is based on theoretical calculations.

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## 8.27 MLX92271LSE-AAA-206-RE

DC Operating Parameters  $V_{DD} = 3.3$  to  $18V$ ,  $T_A = -40^\circ C$  to  $150^\circ C$

Test Condition	Operating Point $B_{OP}$ (mT) <sup>(3)</sup>			Release Point $B_{RP}$ (mT) <sup>(3)</sup>			TC (ppm/ $^\circ C$ )	Output behaviour	Active Pole
	Min	Typ <sup>(1)</sup>	Max	Min	Typ <sup>(1)</sup>	Max			
$T_A = -40^\circ C$	2.2	3.3	4.9	-4.9	-3.3	-2.2	-2200 <sup>(2)</sup>	Latch	South pole
$T_A = 25^\circ C$	1.6	2.8	4.3	-4.3	-2.8	-1.6			
$T_A = 125^\circ C$ <sup>(4)</sup>	0.7	2.2	3.7	-3.7	-2.2	-0.7			
$T_A = 150^\circ C$	0.5	2.0	3.6	-3.6	-2.0	-0.5			

IMC	Safe message	Operating period, ms	Diagnostic period in Fail Safe state, ms	“Output Ticking” duration, $\mu s$	“Output Ticking” repetition period, ms
Yes	FNoDiag	-	-	-	-

## 8.28 MLX92271LSE-AAA-209-RE

DC Operating Parameters  $V_{DD} = 3.3$  to  $18V$ ,  $T_A = -40^\circ C$  to  $150^\circ C$

Test Condition	Operating Point $B_{OP}$ (mT) <sup>(3)</sup>			Release Point $B_{RP}$ (mT) <sup>(3)</sup>			TC (ppm/ $^\circ C$ )	Output behaviour	Active Pole
	Min	Typ <sup>(1)</sup>	Max	Min	Typ <sup>(1)</sup>	Max			
$T_A = -40^\circ C$	6.6	9.4	12.3	-12.3	-9.4	-6.6	-1100 <sup>(2)</sup>	Latch	South pole
$T_A = 25^\circ C$	6.9	8.75	10.6	-10.6	-8.75	-6.9			
$T_A = 150^\circ C$	4.9	7.5	10.5	-10.5	-7.5	-4.9			

IMC	Safe message	Operating period, ms	Diagnostic period in Fail Safe state, ms	“Output Ticking” duration, $\mu s$	“Output Ticking” repetition period, ms
Yes	FNoDiag	-	-	-	-

<sup>1</sup> Unless otherwise specified the typical values are defined at  $T_A = +25^\circ C$  and  $V_{DD} = 12V$ . Melexis production testing is limited to version specific parameters only.

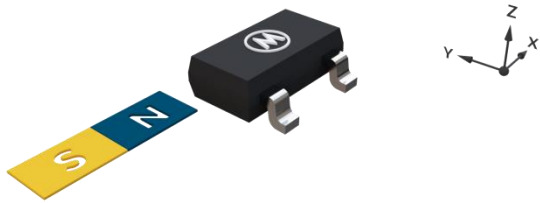
<sup>2</sup> Typical TC programmed. The Temperature Coefficient is calculated using formula from section 8.

<sup>3</sup> Final magnetic parameters will be covered in the PPAP documentation set, the table below is based on theoretical calculations

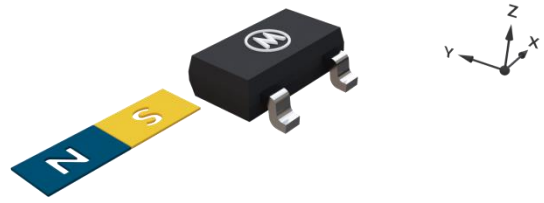
<sup>4</sup> Row “ $T_A = 125^\circ C$ ” is based on theoretical calculations only, not production tested.

# MLX92292/MLX92291/MLX92271

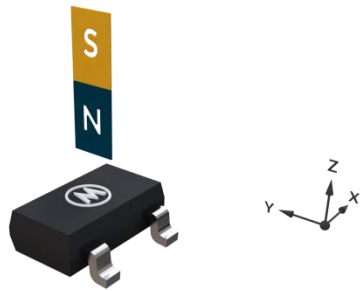
3-wire  $\mu$ Power programmable ASIL B capable Hall Effect Latch/Switch  
Datasheet



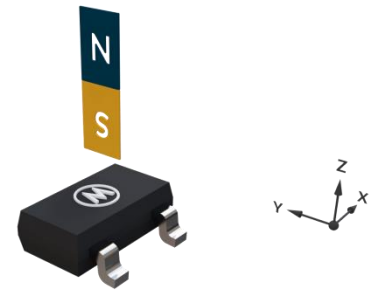
*North active pole (IMC version)*



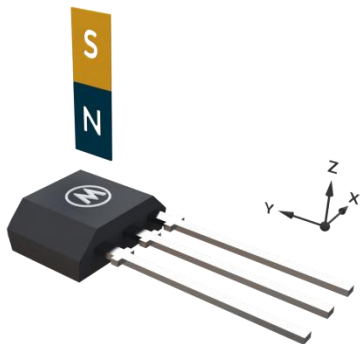
*South active pole (IMC version)*



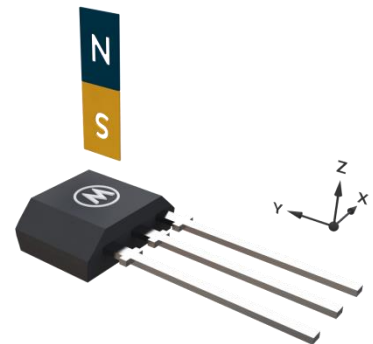
*North active pole*



*South active pole*



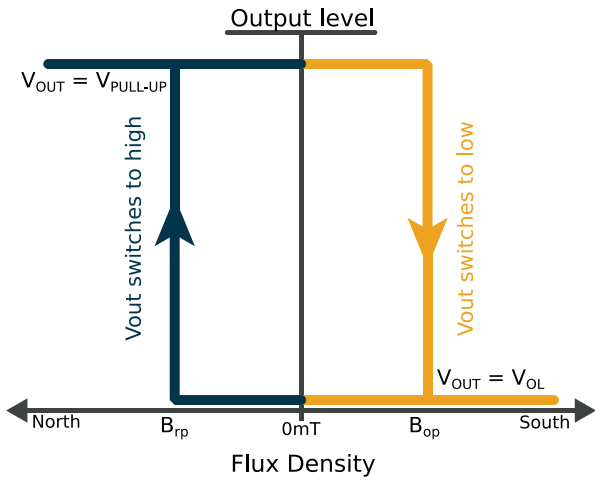
*North active pole*



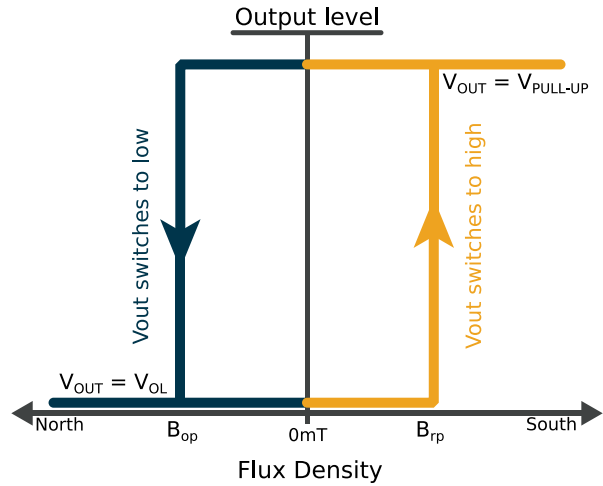
*South active pole*

## 9 Magnetic Behaviour

### 9.1 Latch Sensor

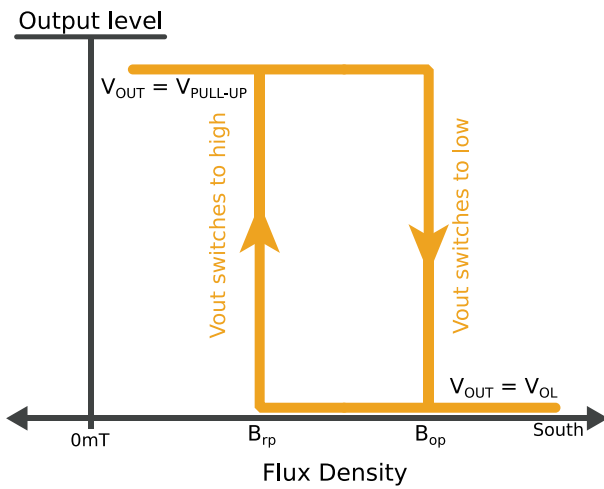


South Pole Active Latch

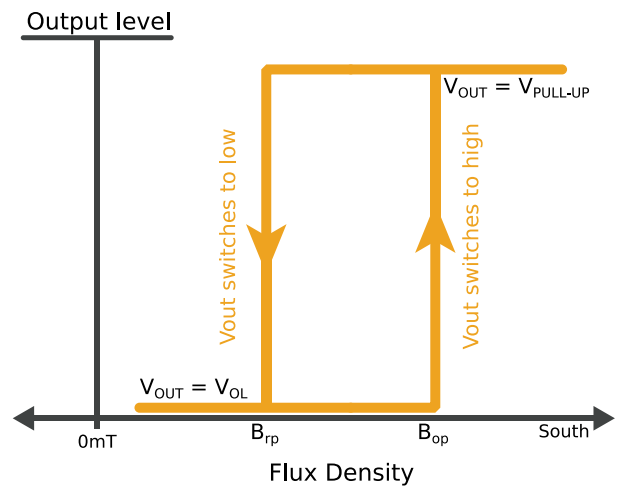


North Pole Active Latch

### 9.2 Unipolar Switch Sensor



Direct South Pole Active Switch

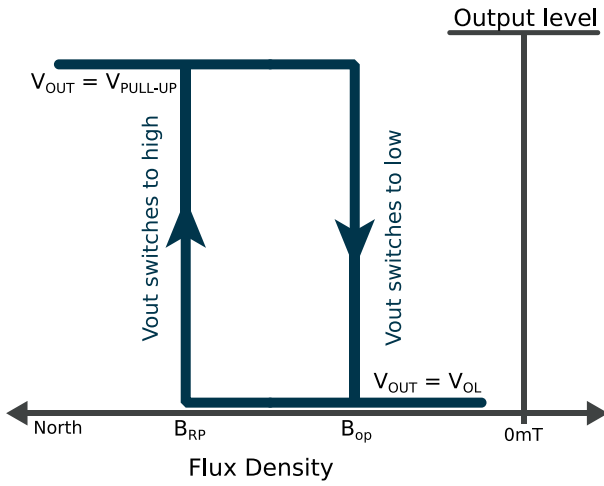


Inverted South Pole Active Switch

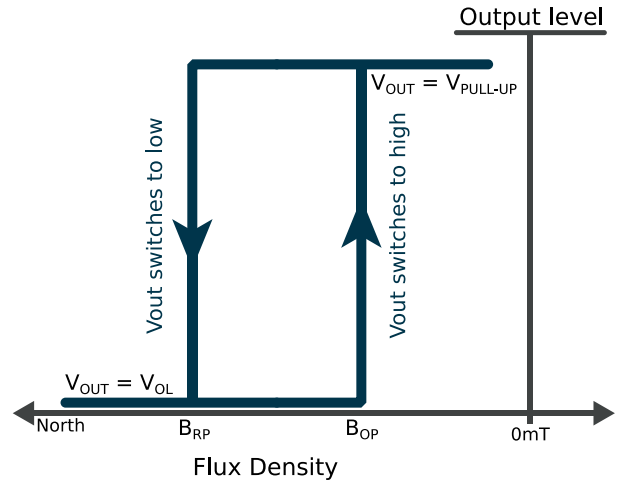
# MLX92292/MLX92291/MLX92271

## 3-wire $\mu$ Power programmable ASIL B capable Hall Effect Latch/Switch

### Datasheet



*Direct North Pole Active Switch*



*Inverted North Pole Active Switch*

# MLX92292/MLX92291/MLX92271

3-wire  $\mu$ Power programmable ASIL B capable Hall Effect Latch/Switch

Datasheet

## 10 Functional Safety Capability

### 10.1 Sensor Development

MLX92292 is developed according to the ISO26262 requirements for ASIL B level.

### 10.2 Technical Safety Requirements

The main (mission) technical safety requirement for MLX92292 is the following:

#### 10.2.1 TS\_RQT\_Mission

ASIL: B

MLX92292 shall not provide wrong information about the detection of presence of magnetic field done by comparing the magnetic field with magnetic thresholds  $B_{op}$  and  $B_{rp}$ , each of them being within a Safe Tolerance Interval (STI) defined in mT as  $\pm a * B_{xp} \pm b$ , where  $B_{xp}$  is the actual magnetic threshold ( $B_{op}$  or  $B_{rp}$ ) and a, b are parameters depending on sensitivity direction and application temperature range. The following table shows the values of a and b for normal and lateral sensitivity device (with IMC) at 25°C and over the full temperature range.

	Ta = 25°C	Ta = -40°C..150°C
<b>Normal (orthogonal) sensitive device</b>	a = 0.18 (18%)	a = 0.22 (22%)
	b = 1.4mT	b = 1.7mT
<b>Lateral sensitive device (with IMC)</b>	a = 0.18 (18%)	a = 0.22 (22%)
	b = 2mT	b = 2.4mT

# MLX92292/MLX92291/MLX92271

## 3-wire $\mu$ Power programmable ASIL B capable Hall Effect Latch/Switch

### Datasheet



## 10.2.2 TS\_RQT\_Safe\_Message

MLX92292 shall report detected failures that could prevent TS\_RQT\_Mission.

One of the following programmable Safe Message options can be chosen depending on the application:

Message Option	B<Brp Diagnostic OK	B>Bop Diagnostic OK	All B values Diagnostic Failed	Diagnostic Coverage	Safe States
<b><math>\mu</math>-Power Mode</b>				<b>SPFM</b>	
TickMsg <sup>(1,2)</sup>	OUT = Off+Ticking	OUT = On+Ticking	OUT = Off	92%	BOP, BRP within STI ; OUT = On/Off w/o ticking
TickOffMsg <sup>(1)</sup>	OUT = Off+Ticking	OUT = On	OUT = Off	82%	BOP, BRP within STI ; OUT = Off
TickOnMsg <sup>(2)</sup>	OUT = Off	OUT = On+Ticking	OUT = On	55%	BOP, BRP within STI ; OUT = On
OutOffMsg	OUT = Off	OUT = On	OUT = Off	82%	BOP, BRP within STI ; OUT = Off
OutOnMsg	OUT = Off	OUT = On	OUT = On	55%	BOP, BRP within STI ; OUT = On
StbyX2Msg <sup>(3)</sup>	OUT = Off	OUT = On	OUT = Off Twice increased T <sub>OP</sub>	77%	BOP, BRP within STI ; Twice increased T <sub>OP</sub>
uNoDiag <sup>(4)</sup>	OUT = Off	OUT = On	-	No diagnostic	BOP, BRP within STI
<b>Fast Mode</b>					
FlddMsg	OUT = Off, I <sub>DD</sub> = I <sub>DDFAST</sub>	OUT = On, I <sub>DD</sub> = I <sub>DDFAST</sub>	OUT = Off, I <sub>DD</sub> = I <sub>DDFAIL</sub>	67%	BOP, BRP within STI ; OUT=Off & I <sub>DD</sub> =I <sub>DDFAIL</sub>
FNoDiag <sup>(4)</sup>	OUT = Off	OUT = On	-	No diagnostic	BOP, BRP within STI

Note (1) Off+Ticking signal means that the Off state duration lasts significantly longer than the On state duration.

Note (2) On+Ticking signal means that the On state duration lasts significantly longer than the Off state duration.

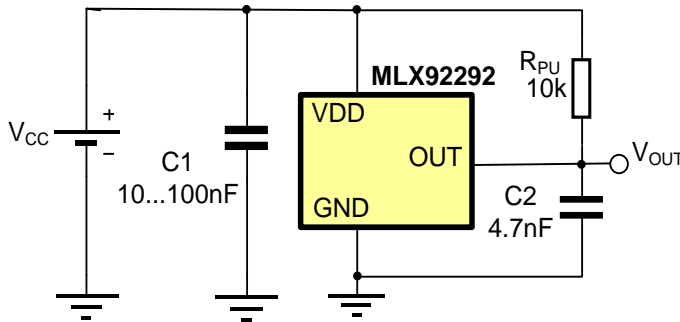
Note (3) If T<sub>OP</sub> is set <5ms then T<sub>OP</sub> increases less than twice in case of diagnostic fail.

Note (4) This message option does not offer integrated diagnostic.



## 11 Application Information

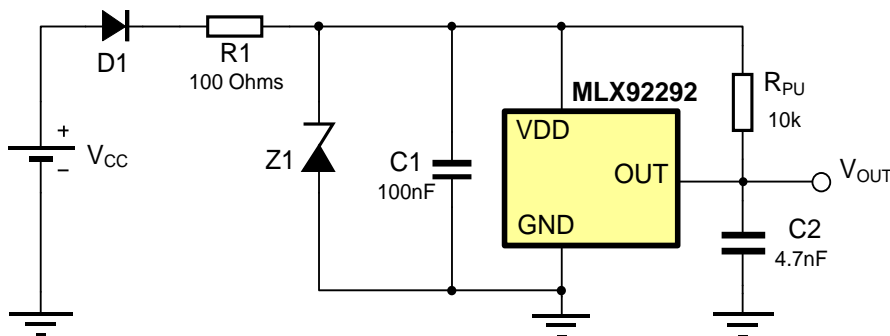
### 11.1 Typical Automotive Application Circuit



**Notes:**

1. For proper operation, a 10nF to 100nF bypass capacitor should be placed as close as possible to the  $V_{DD}$  and ground pin.
2. A capacitor connected to the output will improve the EMC performance

### 11.2 Automotive and Harsh, Noisy Environments Application Circuit



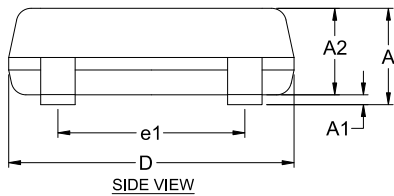
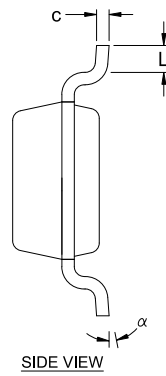
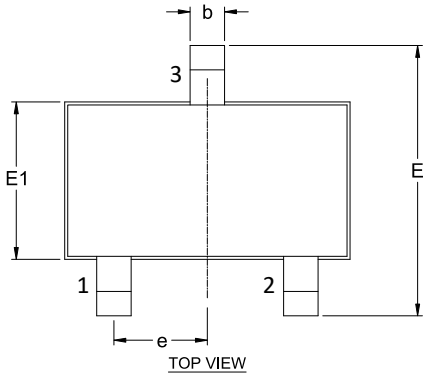
**Notes:**

1. For proper operation the bypass capacitor C1 should be placed as close as possible to the  $V_{DD}$  and GND pins.
2. If negative transients over supply line  $V_{PEAK} < -30V$  are expected, usage of the diode D1 is recommended. Otherwise only R1 is sufficient. When selecting the resistor R1, three points are important:
  - the resistor has to limit  $I_{DD}/I_{DDREV}$  to 40mA maximum
  - the resistor has to withstand the power dissipated in both over voltage conditions ( $V_{R1}^2/R1$ )
  - the resulting device supply voltage  $V_{DD}$  has to be higher than  $V_{DD min}$  ( $V_{DD} = V_{CC} - R1 \cdot I_{DD}$ )
3. If positive transients over supply line with  $V_{PEAK} > 40V$  are expected, usage of Zener diode Z1 is recommended. The R1-Z1 network should be sized to limit the voltage over the device below the maximum allowed.

## 12 Package Information

### 12.1 TSOT-3L (SE Package)

#### 12.1.1 TSOT-3L – Package dimensions

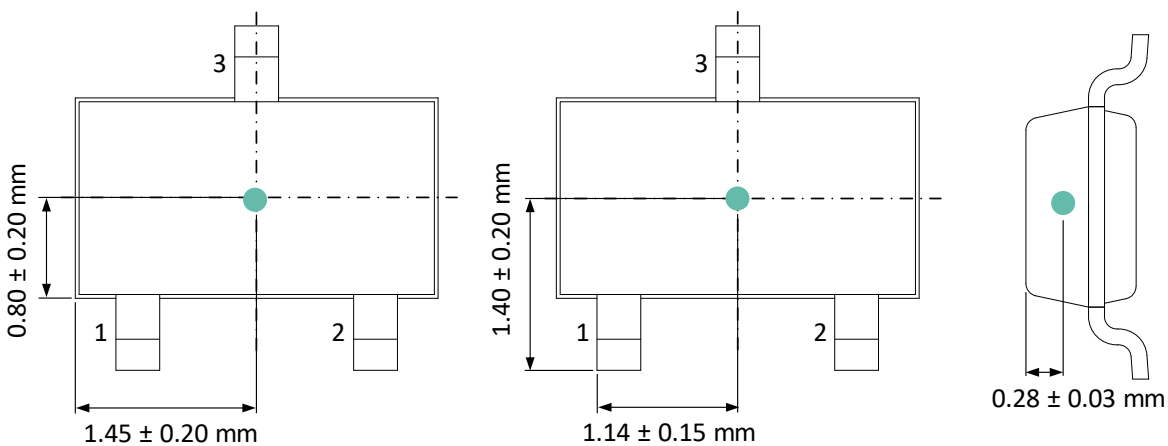


SYMBOL	MINIMUM	MAXIMUM
A	---	1.00
A1	0.025	0.10
A2	0.85	0.90
D	2.80	3.00
E	2.60	3.00
E1	1.50	1.70
L	0.30	0.50
b	0.30	0.45
c	0.10	0.20
e	0.95 BSC	
e1	1.90 BSC	
$\alpha$	0°	8°

NOTE :

1. ALL DIMENSIONS IN MILLIMETERS (mm) UNLESS OTHERWISE STATED.
2. DIMENSION D DOES NOT INCLUDE MOLD FLASH OR PROTRUSIONS OF MAX 0.15 mm PER SIDE.
3. DIMENSION E DOES NOT INCLUDE MOLD FLASH OR PROTRUSIONS OF MAX 0.25 mm PER SIDE.
4. DIMENSION b DOES NOT INCLUDE DAMBAR PROTRUSION OF MAX 0.07 mm.
5. DIMENSION L IS THE LENGTH OF THE TERMINAL FOR SOLDERING TO A SUBSTRATE.
6. FORMED LEAD SHALL BE PLANAR WITH RESPECT TO ONE ANOTHER WITH 0.076 mm SEATING PLANE.

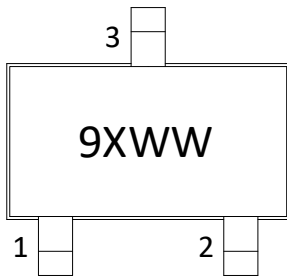
#### 12.1.2 TSOT-3L – Sensitive spot



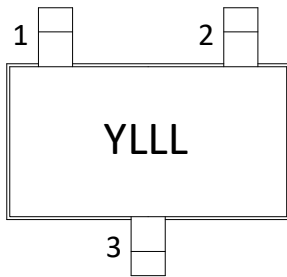
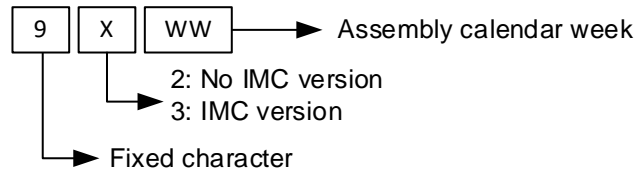
# MLX92292/MLX92291/MLX92271

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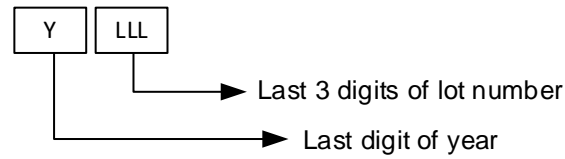
## 12.1.3 TSOT-3L – Package marking / Pin definition



### Top



### Bottom



Pin #	Name	Type	Function
1	VDD	Supply	Supply Voltage pin
2	OUT	Out	Open drain output pin
3	GND	Ground	Ground pin

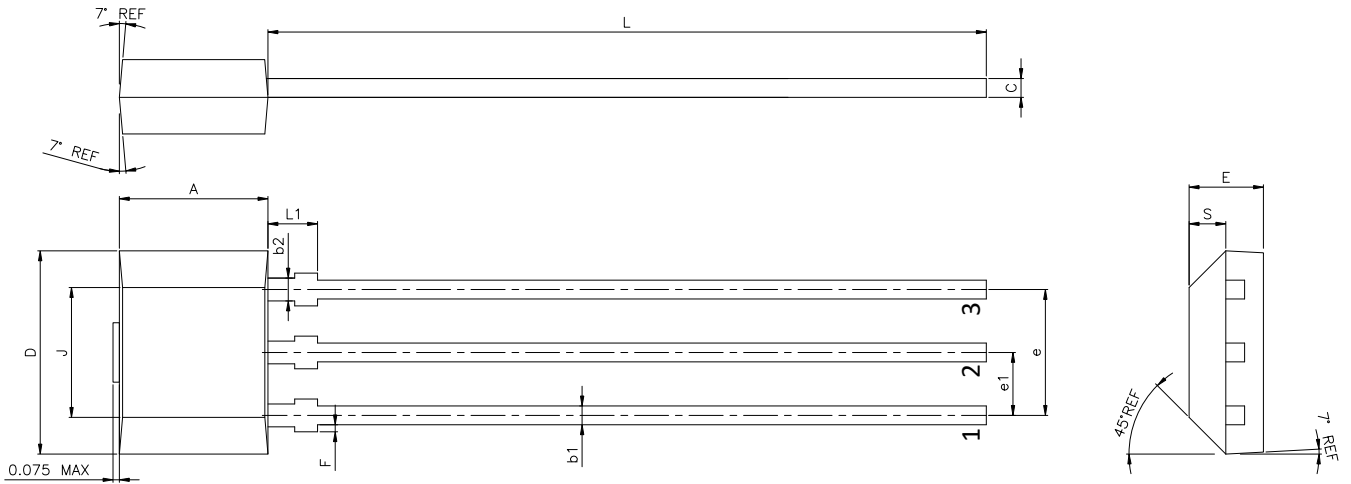
# MLX92292/MLX92291/MLX92271

3-wire  $\mu$ Power programmable ASIL B capable Hall Effect Latch/Switch

Datasheet

## 12.2 TO92-3L (UA Package)

### 12.2.1 TO92-3L – Package dimensions

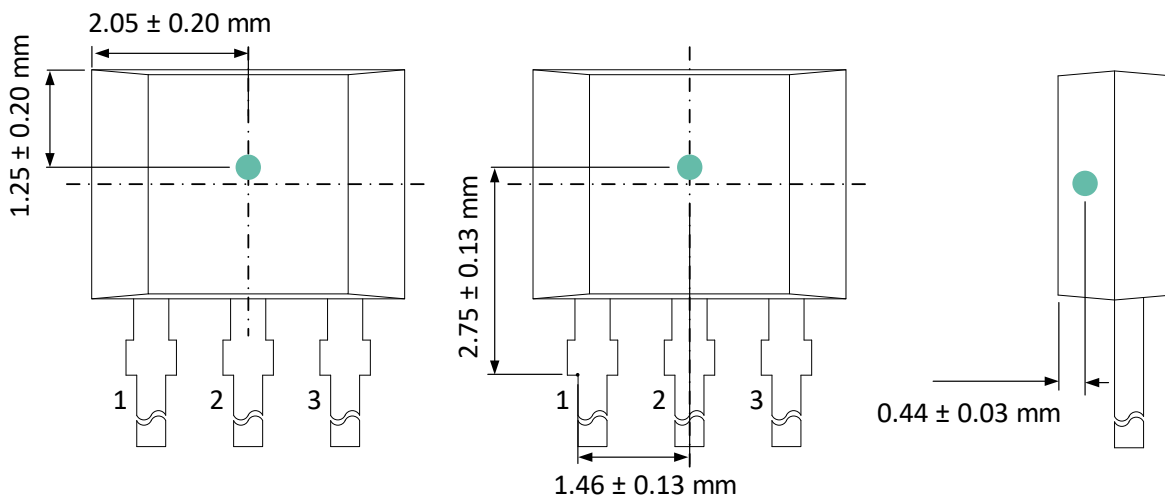


SYMBOL	MINIMUM	MAXIMUM
A	2.90	3.10
D	4.00	4.20
E	1.40	1.60
F	0.00	0.15
J	2.51	2.72
L	14.00	15.00
L1	0.90	1.10
S	0.63	0.84
b1	0.35	0.44
b2	0.43	0.52
c	0.35	0.44
e	2.51	2.57
e1	1.24	1.30

NOTES :

1. DIMENSIONS IN MILLIMETERS (mm) UNLESS NOTED OTHERWISE.
2. PACKAGE DIMENSIONS DO NOT INCLUDE MOLD FLASHES AND PROTRUSIONS.
3. DIMENSION A AND D DO NOT INCLUDE MOLD GATE AND SIDE FLASH (PROTRUSION) of MAXIMUM 0.127 mm PER SIDE.
4. THE LEADS MAY BE SLIGHTLY DEFORMED DURING TRANSPORTATION IF PACKED IN BULK (BAG), AFFECTING e1 DIMENSION. IT IS RECOMMENDED TO ORDER RADIAL TAPE (REEL OR AMMOPACK) IF SUCH DEFORMATION IS CRITICAL FOR THE LEAD FORMING PROCESS, EVEN IF MANUAL LOADING INTO THE TOOL IS FORESEEN.

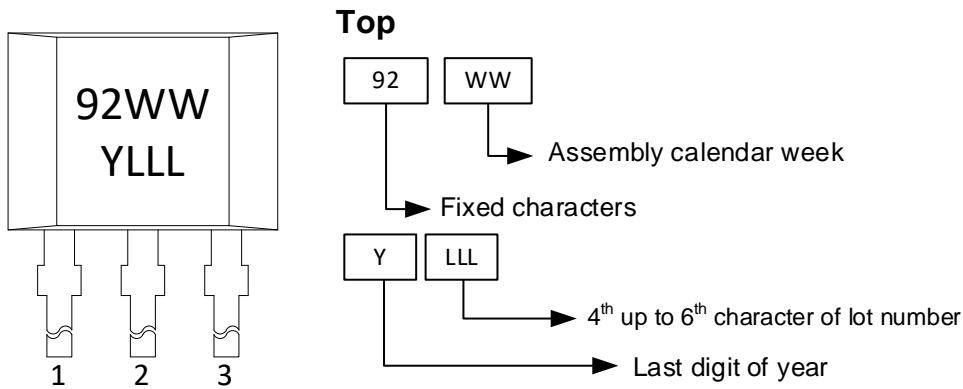
### 12.2.2 TO92-3L – Sensitive spot



# MLX92292/MLX92291/MLX92271

3-wire  $\mu$ Power programmable ASIL B capable Hall Effect Latch/Switch  
Datasheet

## 12.2.3 TO92-3L – Package marking / Pin definition



Pin #	Name	Type	Function
1	VDD	Supply	Supply Voltage pin
2	GND	Ground	Ground pin
3	OUT	Out	Open drain output pin

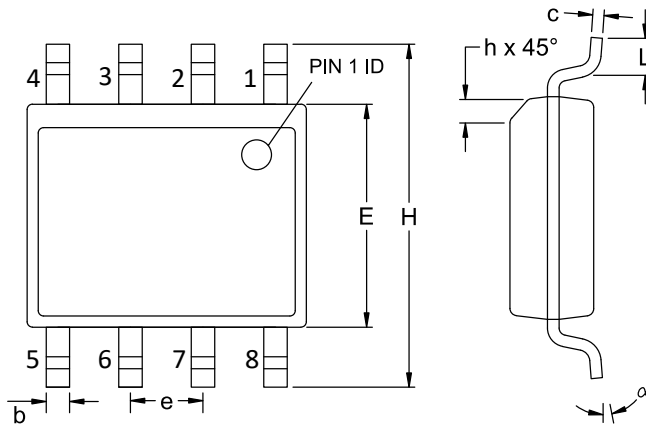
# MLX92292/MLX92291/MLX92271

3-wire  $\mu$ Power programmable ASIL B capable Hall Effect Latch/Switch

Datasheet

## 12.3 SOIC8 (DC Package)

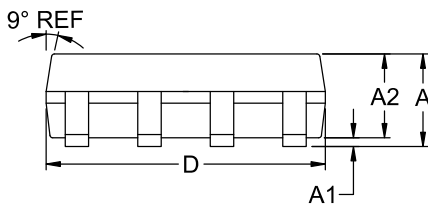
### 12.3.1 SOIC8– Package dimensions



TOP VIEW

SIDE VIEW

SYMBOL	MINIMUM	MAXIMUM
A	1.52	1.73
A1	0.10	0.25
A2	1.37	1.57
D	4.80	4.98
E	3.81	3.99
H	5.80	6.20
L	0.41	1.27
b	0.35	0.49
c	0.19	0.25
h	0.25	0.50
e	1.27 BSC	
$\alpha$	0°	8°

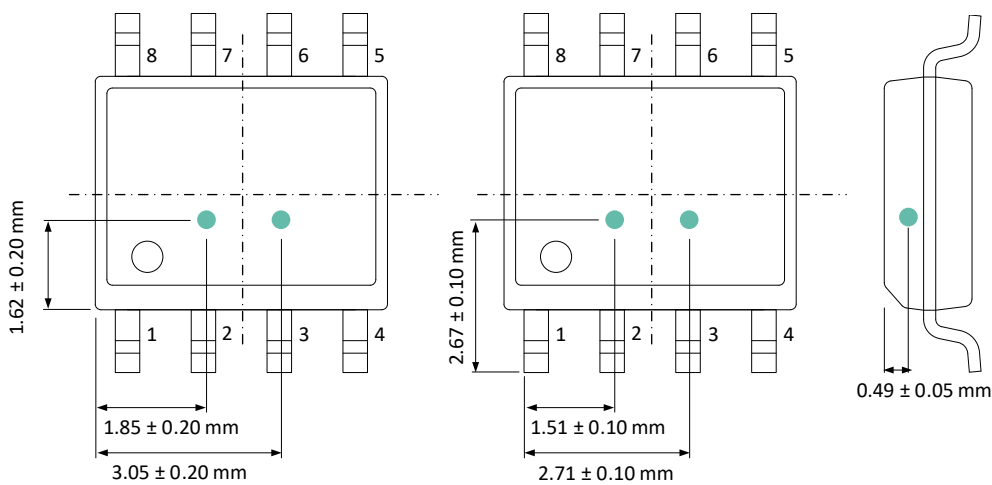


SIDE VIEW

NOTE :

1. ALL DIMENSIONS IN MILLIMETERS (mm) UNLESS OTHERWISE STATED.
2. DIMENSION D DOES NOT INCLUDE MOLD FLASH, PROTRUSIONS OR GATE BURRS OF MAX 0.15 mm PER SIDE.
3. DIMENSION E DOES NOT INCLUDE INTERLEADS FLASH OR PROTRUSIONS OF MAX 0.25 mm PER SIDE.
4. DIMENSION b DOES NOT INCLUDE DAMBAR PROTRUSION OF MAX 0.08 mm.

### 12.3.2 SOIC8– Sensitive spot

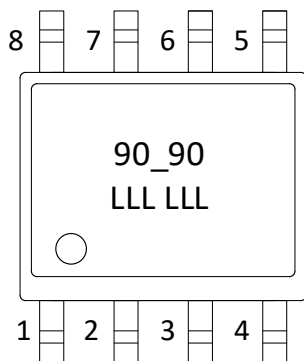


# MLX92292/MLX92291/MLX92271

3-wire  $\mu$ Power programmable ASIL B capable Hall Effect Latch/Switch

Datasheet

## 12.3.3 SOIC8– Package marking / Pin definition

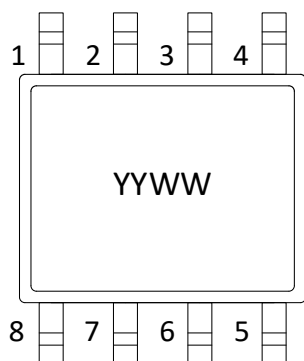


### Marking

#### Top side

90\_90 → Device name

LLL LLL → Last 3 digits of assembly lot# from each die



#### Bottom side

YY WW → Calender week (WW)

→ Calender Year (YY)

Pin #	Name	Type	Function
1	GND2	Ground	Ground pin DIE 2
2	OUT2	Output	Output DIE 2
3	N.C.		Not connected
4	OUT1	Output	Output DIE 1
5	GND1	Ground	Ground DIE 1
6	VDD1	Supply	Supply DIE 1
7	N.C.		Not connected
8	VDD2	Supply	Supply DIE 2

## 13 IC handling and assembly

### 13.1 Storage and handling of plastic encapsulated ICs

Plastic encapsulated ICs shall be stored and handled according to their MSL categorization level (specified in the packing label) as per J-STD-033.

Electronic semiconductor products are sensitive to Electro Static Discharge (ESD). The component assembly shall be handled in EPA (Electrostatic Protected Area) as per ANSI S20.20

For more information refer to Melexis [Guidelines for storage and handling of plastic encapsulated ICs](#)<sup>(1)</sup>

### 13.2 Assembly of encapsulated ICs

For Surface Mounted Devices (SMD, as defined according to JEDEC norms), the only applicable soldering method is reflow.

For Through Hole Devices (THD), the applicable soldering methods are reflow, wave, selective wave and robot point-to-point. THD lead pre-forming (cutting and/or bending) is applicable under strict compliance with Melexis [Guidelines for lead forming of SIP Hall Sensors](#)<sup>(1)</sup>.

Melexis products soldering on PCB should be conducted according to the requirements of IPC/JEDEC and J-STD-001. Solder quality acceptance should follow the requirements of IPC-A-610.

For PCB-less assembly refer to the relevant application notes <sup>(1)</sup> or contact Melexis.

Electrical resistance welding or laser welding can be applied to Melexis products in THD and specific PCB-less packages following the [Guidelines for welding of PCB-less devices](#)<sup>(1)</sup>.

Environmental protection of customer assembly with Melexis products for harsh media application, is applicable by means of coating, potting or overmolding considering restrictions listed in the relevant application notes <sup>(1)</sup>

For other specific process, contact Melexis via [www.melexis.com/technical-inquiry](http://www.melexis.com/technical-inquiry)

### 13.3 Environment and sustainability

Melexis is contributing to global environmental conservation by promoting non-hazardous solutions. For more information on our environmental policy and declarations (RoHS, REACH...) visit [www.melexis.com/environmental-forms-and-declarations](http://www.melexis.com/environmental-forms-and-declarations)



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